



Transportation Data Potpourri in Frisco

TexITE Joint Dallas-Fort Worth Section Meeting
May 11, 2018

Curtis Jarecki, P.E.
Brian Moen, P.E.
City of Frisco

Overview

- Signal Performance Measures
- Signal Data Sharing
- Waze Traffic Data
- Closest To Dispatching
- Autonomous Vehicles
- What's Next For Frisco?





Road Map for SPM

- Detection Requirements for SPM
- Detection Setup Examples
- Detection Standard
- Example – Occupancy on Green
- Example – Phase Termination
- Example – Crowd Travel Time



PROGRESS IN MOTION

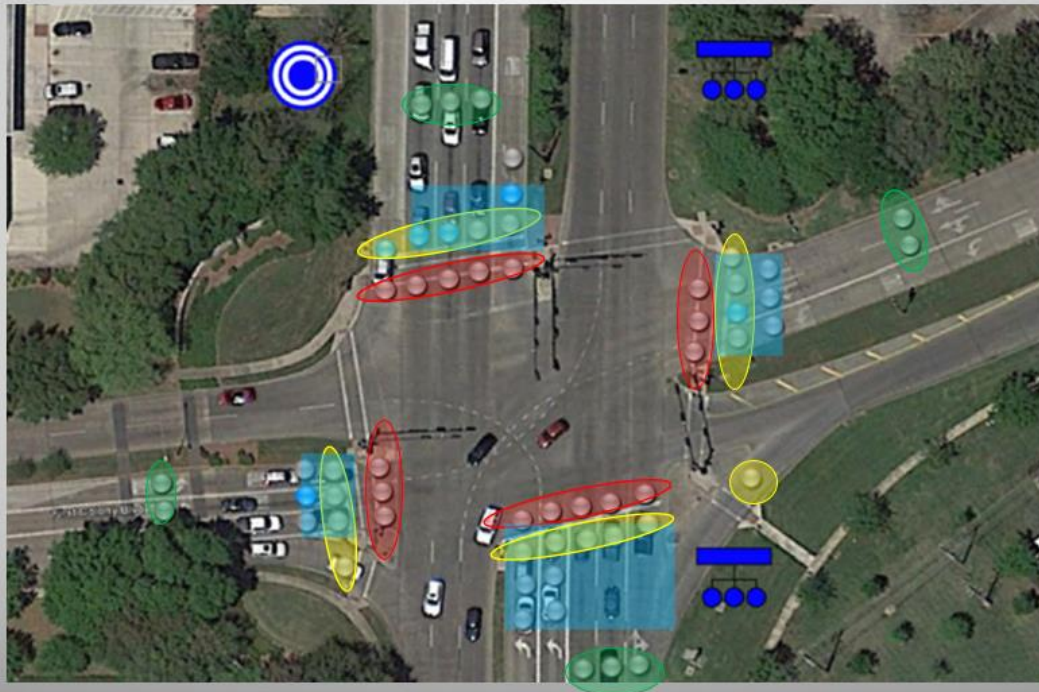
Detection Requirements



SIGNAL PERFORMANCE MEASURES



TYPICAL DETECTION REQUIREMENTS



- STOP BAR
- RED LIGHT MONITOR
- TURNING MOVEMENT
- ADVANCE



PROGRESS IN MOTION

Detection Requirements



SIGNAL PERFORMANCE MEASURES



DETECTION REQUIREMENTS

	ADVANCE DETECTOR	RED LIGHT MONITOR (RLM)	STOP BAR DETECTOR	TURNING MOVEMENT COUNT (TMC)
APPROACH DELAY	✓			
APPROACH VOLUME	✓			
ARRIVALS ON RED	✓			
PEDESTRIAN DELAY				
PREEMPTION DETAILS				
PURDUE COORDINATION DIAGRAM	✓			
PURDUE PHASE TERMINATION				
PURDUE SPLIT FAILURE			✓	
SPLIT MONITOR				
TURNING MOVEMENT COUNTS				✓
YELLOW AND RED ACTUATIONS		✓		



Detector Requirements

- 11 Standard SPMs
- 4 of 11 with ATC controller
- 3 of 11 with most stop bar detection
- 4 of 11 with setback detection

Stop Bar Setup - Video





PROGRESS IN MOTION

Stop Bar Setup - RADAR

Sensor Setup

1 2 3-Verification

1 N	2 N	3 N	4 N	5 N	6 N	7 N	8 N
--------	--------	--------	--------	--------	--------	--------	--------

SB

A diagram showing a road with two lanes. The left lane has a white arrow pointing left, and the right lane has a white arrow pointing right. Green rectangular boxes represent sensor zones: one in the left lane and two in the right lane. A yellow curved area on the left represents the radar's field of view.

Navigation icons: back, save, waveform, zoom, play/pause, help, and up arrow.

& Veneto SB

Playback

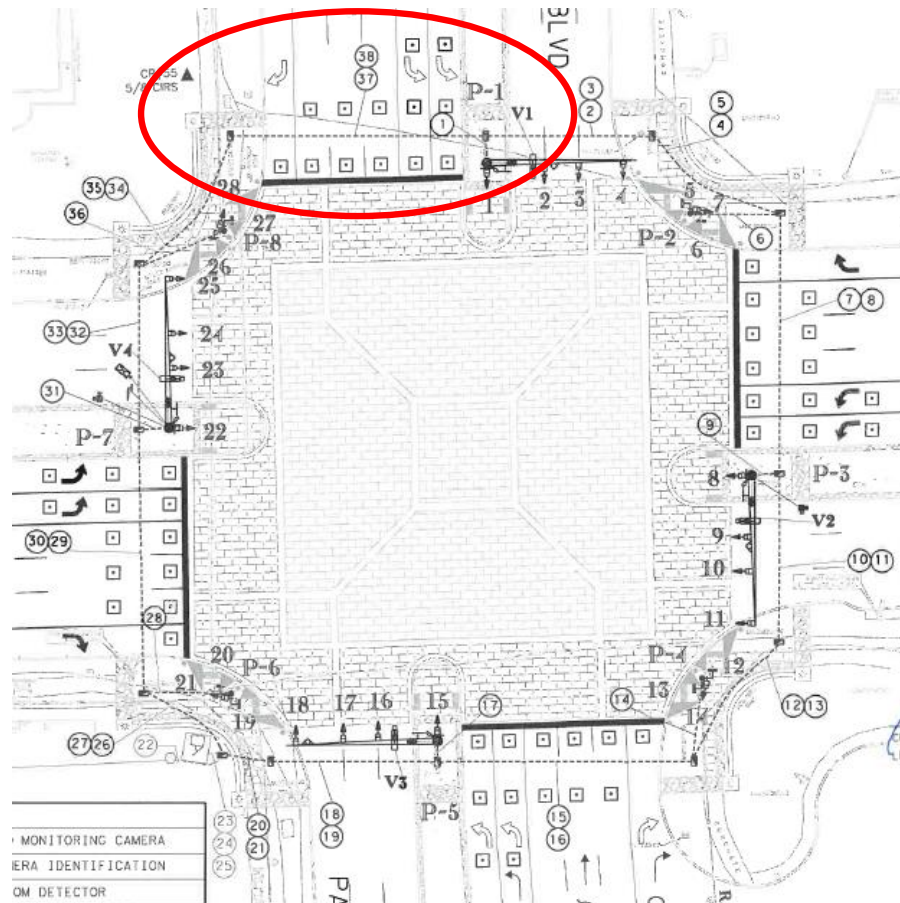
Link window

view >

acy & Veneto SB

A live video feed showing a road intersection. The road has a white stop bar and a white arrow pointing right. The video player interface includes a zoom in (+) button and a 'More' dropdown menu.

Stop Bar - Magnetometers



Setback Setup - General

- Where to put the setback detection point(s)?
Some things to consider:
 - Performance Measures
 - Dilemma Zone Protection
 - Operational Efficiency
 - Adaptive Control Needs

Setback Setup - General

- Performance Measures
 - Ideal is farther back than the maximum queue length.
- Dilemma Zone Protection
 - 5.5 seconds away 90% stop
 - 2.5 seconds away 10% stop
- Operational Efficiency
 - ~2.5 seconds (varies with speed & zone size)
- Adaptive Control Needs
 - Works with what is best for other considerations

Setback Setup - General

- Performance Measures
- Dilemma Zone Protection
 - 5.5 seconds away 90% stop
 - 2.5 seconds away 10% stop
- Operational Efficiency
 - ~2.5 seconds (varies with speed & zone size)
- ~~Adaptive Control Needs~~

Setback Setup - General

- Performance Measures – another detection point could be added
- Dilemma Zone Protection – 3 second extension (gap time)
 - 5.5 seconds away 90% stop
 - 2.5 seconds away 10% stop
- Operational Efficiency – about 2.5 second extension
- One has to choose between dilemma zone and operational efficiency



PROGRESS IN MOTION

Setback Setup - RADAR

Verify Channels-Alerts-Zones

Channels

900			
850			
800			
750			
700			
650	630	45	9.5
600			
550			
500	490	54	6.1
450	455	35	8.8
400	390	29	9.1
350			
300			
250			
200			
150	150	32	3.1
100			
40			

feet

Scale Range | Speed | ETA All

Dilemma S

SPM Pu

Channel3

Channel4

Channel5

Channel6

Channel7

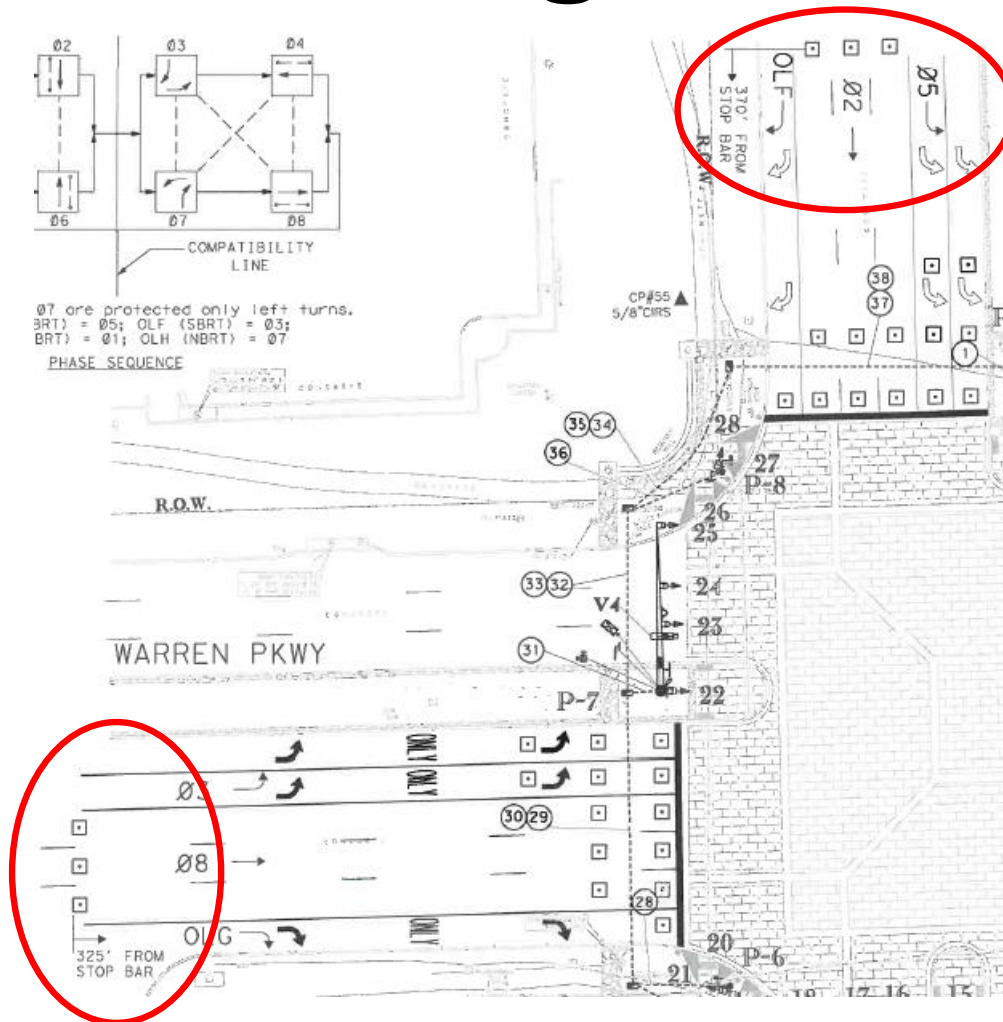
Channel8





PROGRESS IN MOTION

Setback - Magnetometers





Detection Standard

- Standard for
 - Standard Intersection
 - Diamond Intersection
 - Box Diamond Intersection
- Detector Inputs
 - Need 128 (8 BUIs) detector inputs.
 - 64 (4 BUIs) is not enough.



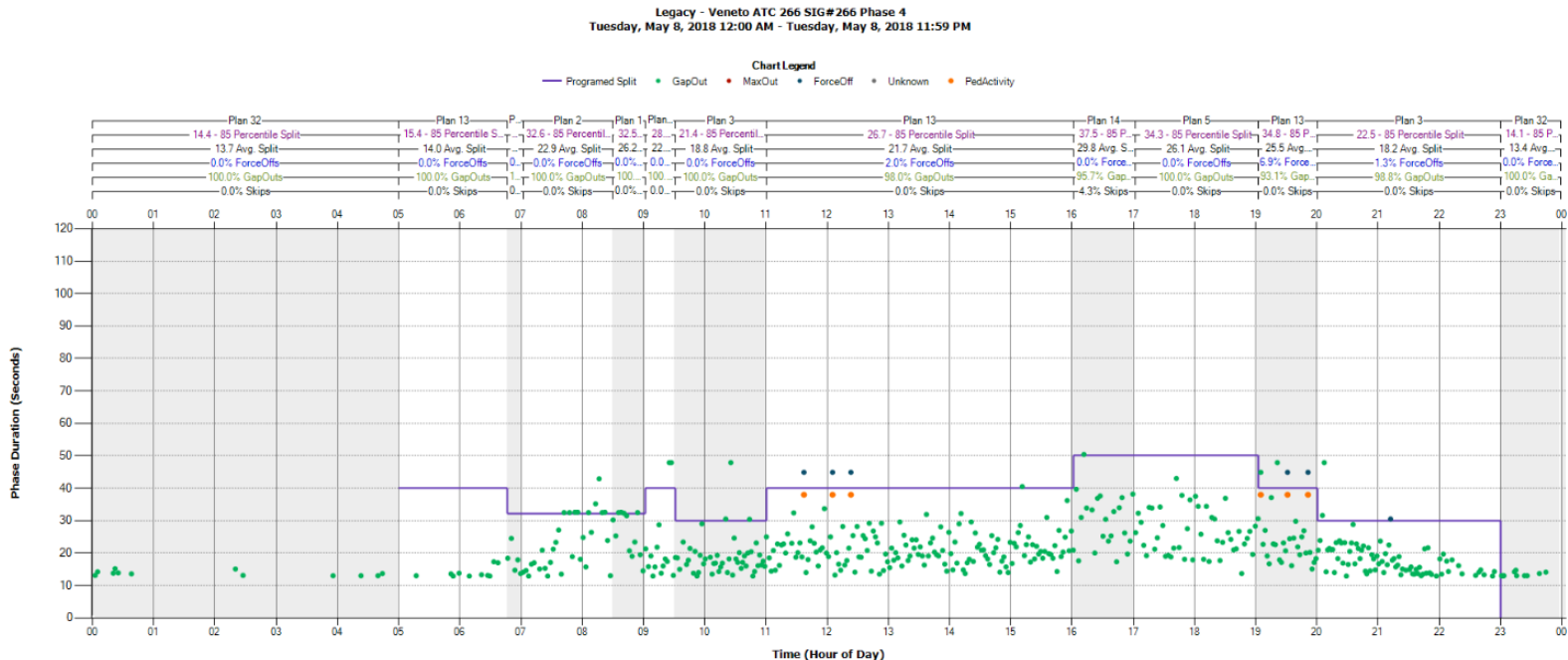
PROGRESS IN MOTION

Detection Standard

Standard 8													
BIU 9					BIU 10					BIU 11		BIU 12	
Pin	Label - Phase	Source	Func		Detector	Phase	Source	Func		Detector	Phase	Detector	Phase
Base					Setbacks					NB Counting		EB Counting	
1	NBLT - Ph 1	field	C, Ext		17	NB Setback (1)	field	C, Ext		33	NB U-Turn	49	EB U-Turn
2	SB - Ph 2	field	C, Ext		18	NB Setback (2)	field	C, Ext		34	NB LT (1)	50	EB LT (1)
3	EBLT - Ph 3	field	C, Ext		19	SB Setback (1)	field	C, Ext		35	NB LT (2)	51	EB LT (2)
4	WB - Ph 4	field	C, Ext		20	SB Setback (2)	field	C, Ext		36	NB Thru (1)	52	EB Thru (1)
5	SBLT - Ph 5	field	C, Ext		21	EB Setback (1)	field	C, Ext		37	NB Thru (2)	53	EB Thru (2)
6	NB - Ph 6	field	C, Ext		22	EB Setback (2)	field	C, Ext		38	NB Thru (3)	54	EB Thru (3)
7	WBLT - Ph 7	field	C, Ext		23	WB Setback (1)	field	C, Ext		39	NB Thru (4) or 2nd NBRT (LL)	55	EB Thru (4) or 2nd EBRT (LL)
8	EB - Ph 8	field	C, Ext		24	WB Setback (2)	field	C, Ext		40	NBRT (1 or RL)	56	EBRT (1 or RL)
RT/Double Cycle					FYA					SB Counting		WB Counting	
9	EBRT - Ph 1 or 8	field	C, Ext		25	FYA - NBLT (Ph 1)	1	C, Ext		41	SB U-Turn	57	WB U-Turn
10	SBRT - Ph 3 or 2	field	C, Ext		26	FYA - NBLT (Ph 9)	1	C, Ext		42	SB LT (1)	58	WB LT (1)
11	WBRT - Ph 5 or 4	field	C, Ext		27	FYA - EBLT (Ph 3)	3	C, Ext		43	SB LT (2)	59	WB LT (2)
12	NBRT - Ph 7 or 6	field	C, Ext		28	FYA - EBLT (Ph 11)	3	C, Ext		44	SB Thru (1)	60	WB Thru (1)
13	RT/Double #1	varies	C, Ext		29	FYA - SBLT (Ph 5)	5	C, Ext		45	SB Thru (2)	61	WB Thru (2)
14	RT/Double #2	varies	C, Ext		30	FYA - SBLT (Ph 13)	5	C, Ext		46	SB Thru (3)	62	WB Thru (3)
15	RT/Double #3	varies	C, Ext		31	FYA - WBLT (Ph 7)	7	C, Ext		47	SB Thru (4) or 2nd SBRT (LL)	63	WB Thru (4) or 2nd WBRT (LL)
16	RT/Double #4	varies	C, Ext		32	FYA - WBLT (Ph 15)	7	C, Ext		48	SBRT (1 or RL)	64	WBRT (1 or RL)

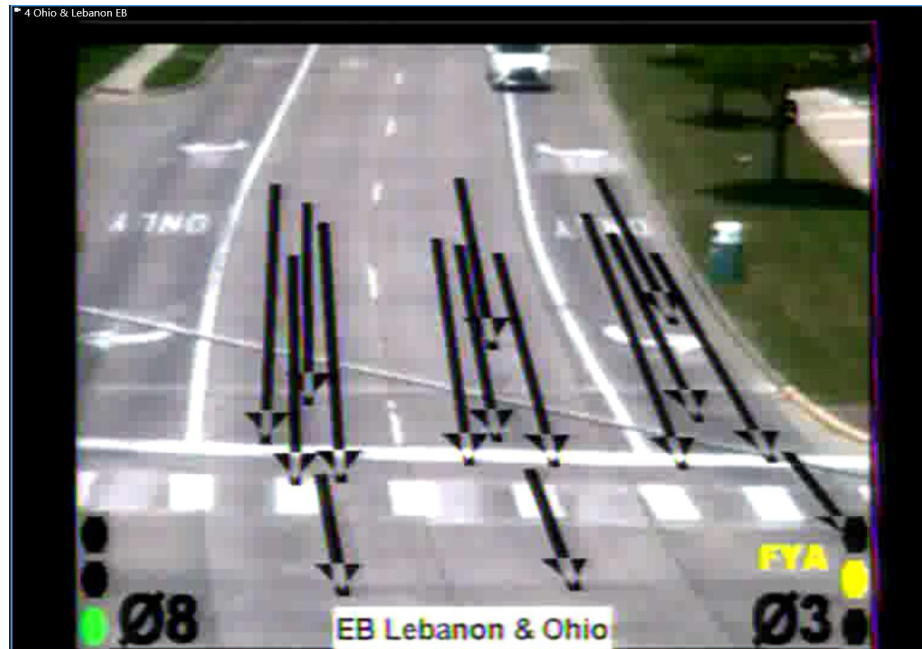
SPM

- SPM presents data in ways not seen but
- How does a point on a chart relate to the traffic conditions?



Purdue Split Failure

- The chart versus the real world.
- Collected the data for Purdue Split Failure and recorded the approach for a day.

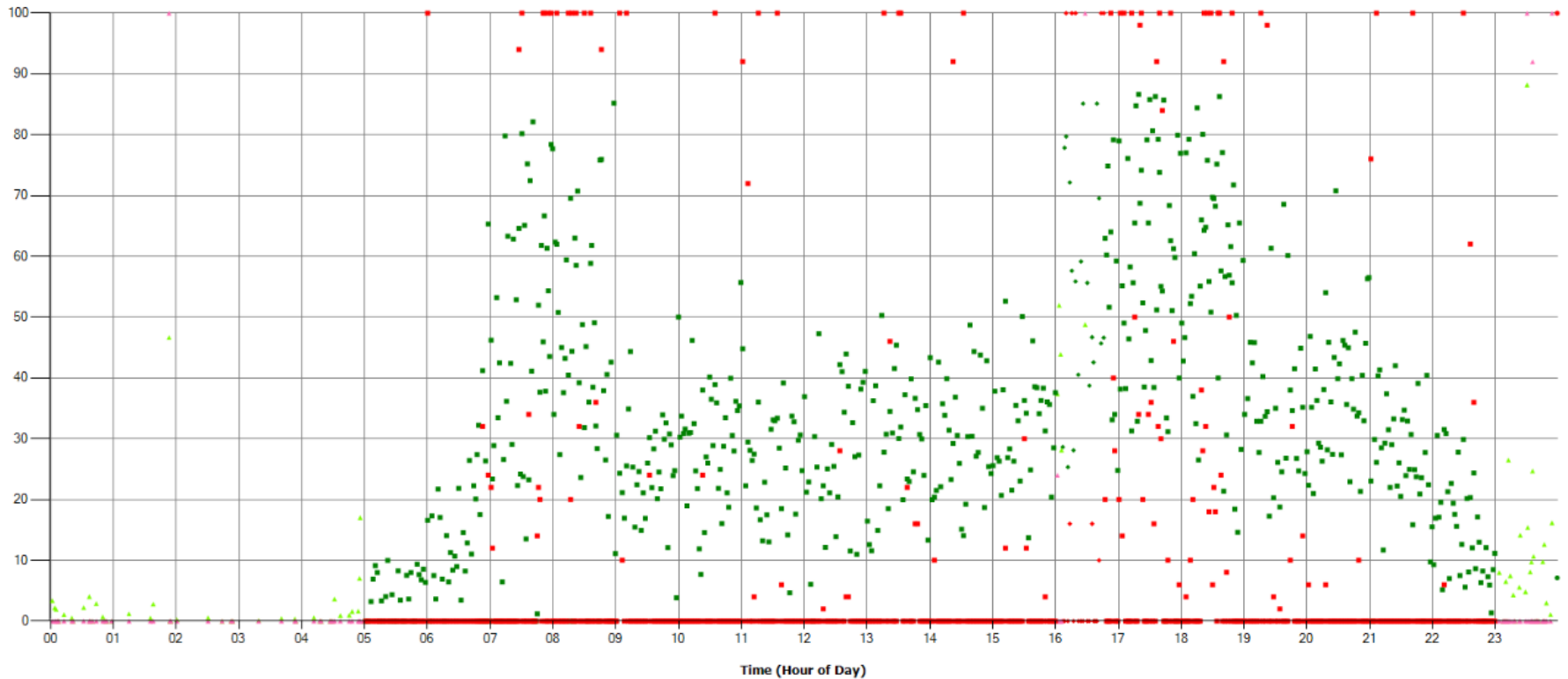




PROGRESS IN MOTION

Purdue Split Failure

Ohio - Lebanon ATC 716 Signal 716 Phase: 8 Eastbound
Tuesday, May 8, 2018 12:00 AM - Tuesday, May 8, 2018 11:59 PM



Purdue Split Failure

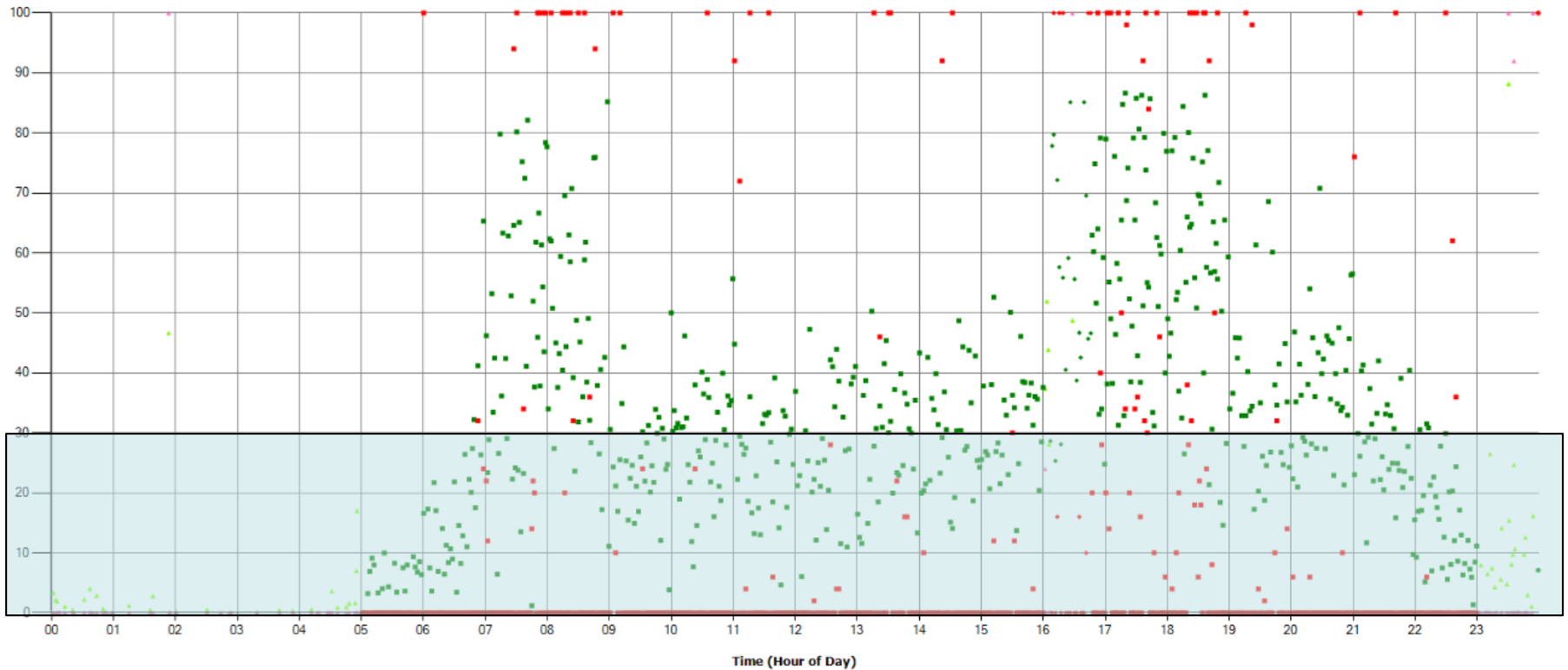
- Green dots are the occupancy ratio during the green
- Red dots are the occupancy ratio during the first 5 seconds of the red



PROGRESS IN MOTION

Case 1 – 0 to 30% GOR

Ohio - Lebanon ATC 716 Signal 716 Phase: 8 Eastbound
Tuesday, May 8, 2018 12:00 AM - Tuesday, May 8, 2018 11:59 PM





PROGRESS IN MOTION

Case 1 – 0 to 30% GOR

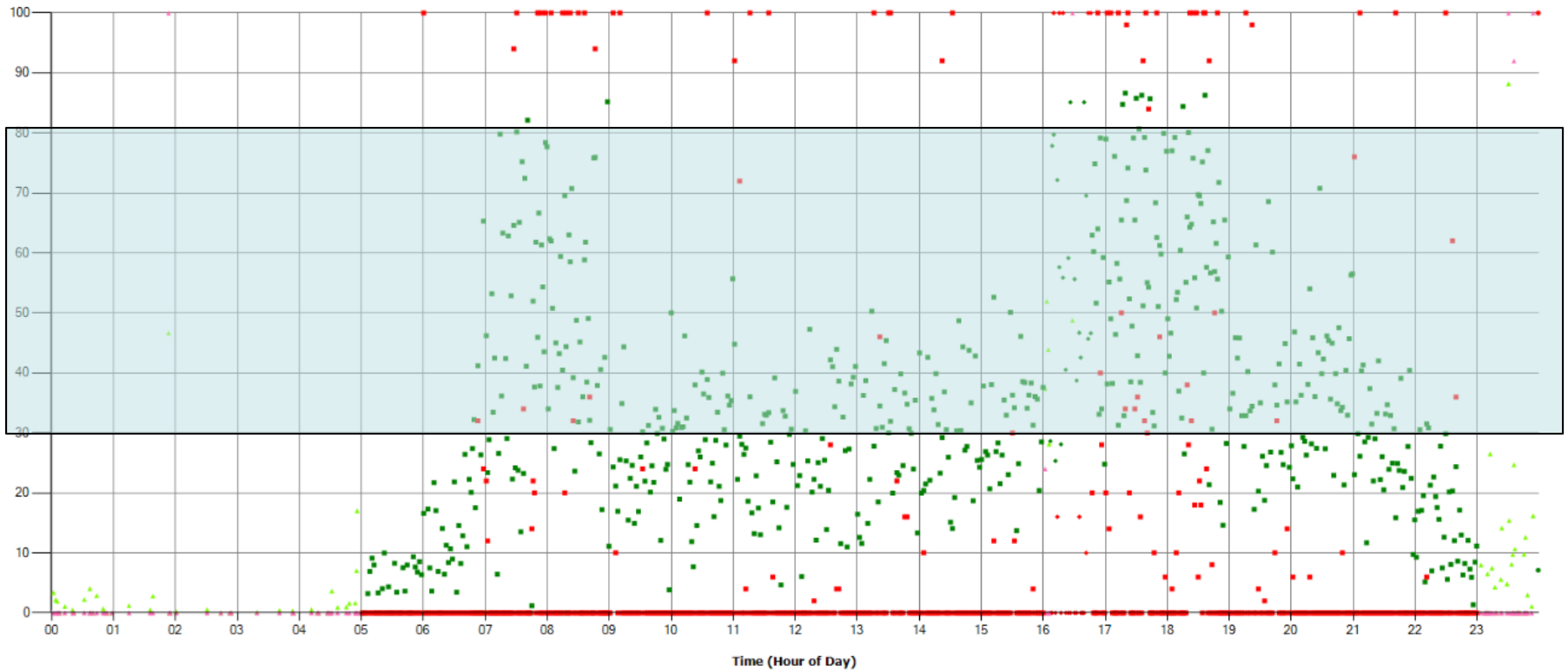




PROGRESS IN MOTION

Case 2 – 30 to 80% GOR

Ohio - Lebanon ATC 716 Signal 716 Phase: 8 Eastbound
Tuesday, May 8, 2018 12:00 AM - Tuesday, May 8, 2018 11:59 PM





PROGRESS IN MOTION

Case 2 – 30 to 80% GOR

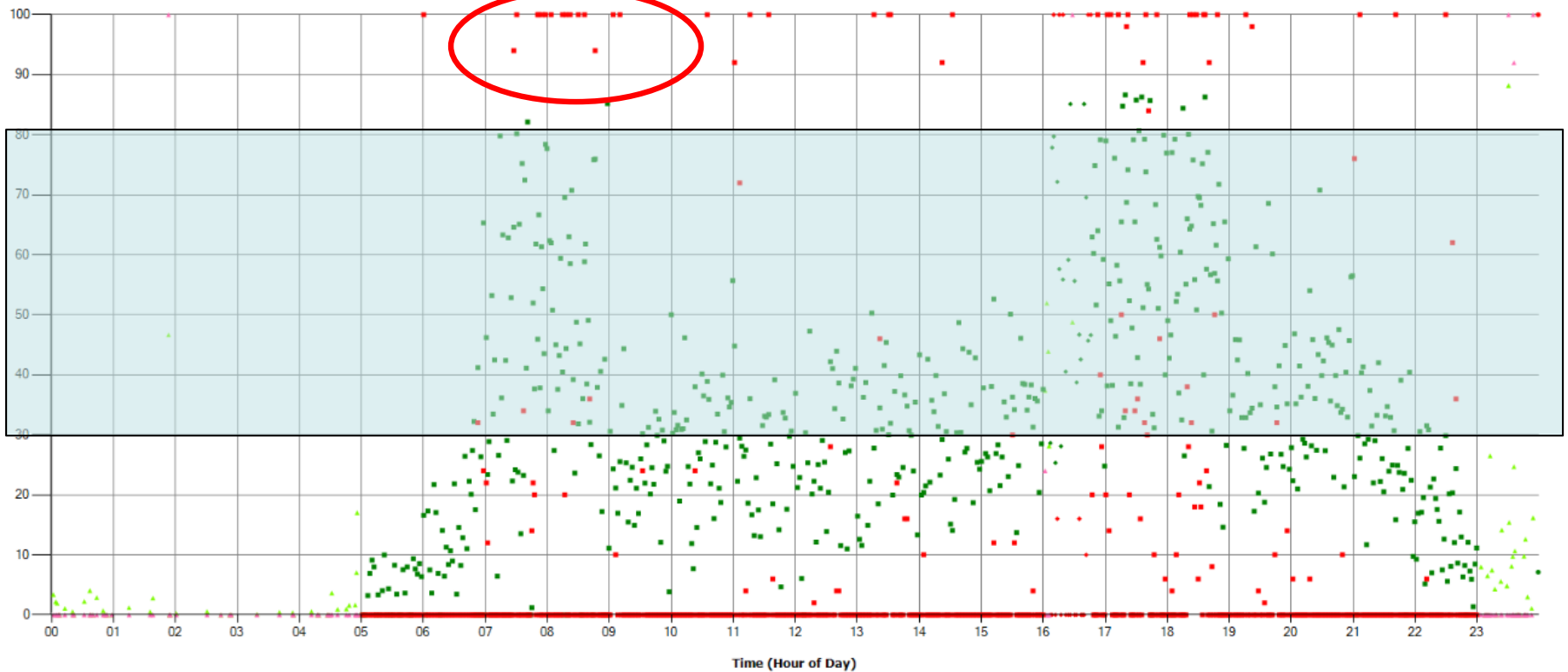




PROGRESS IN MOTION

Case 2 – 30 to 80% GOR

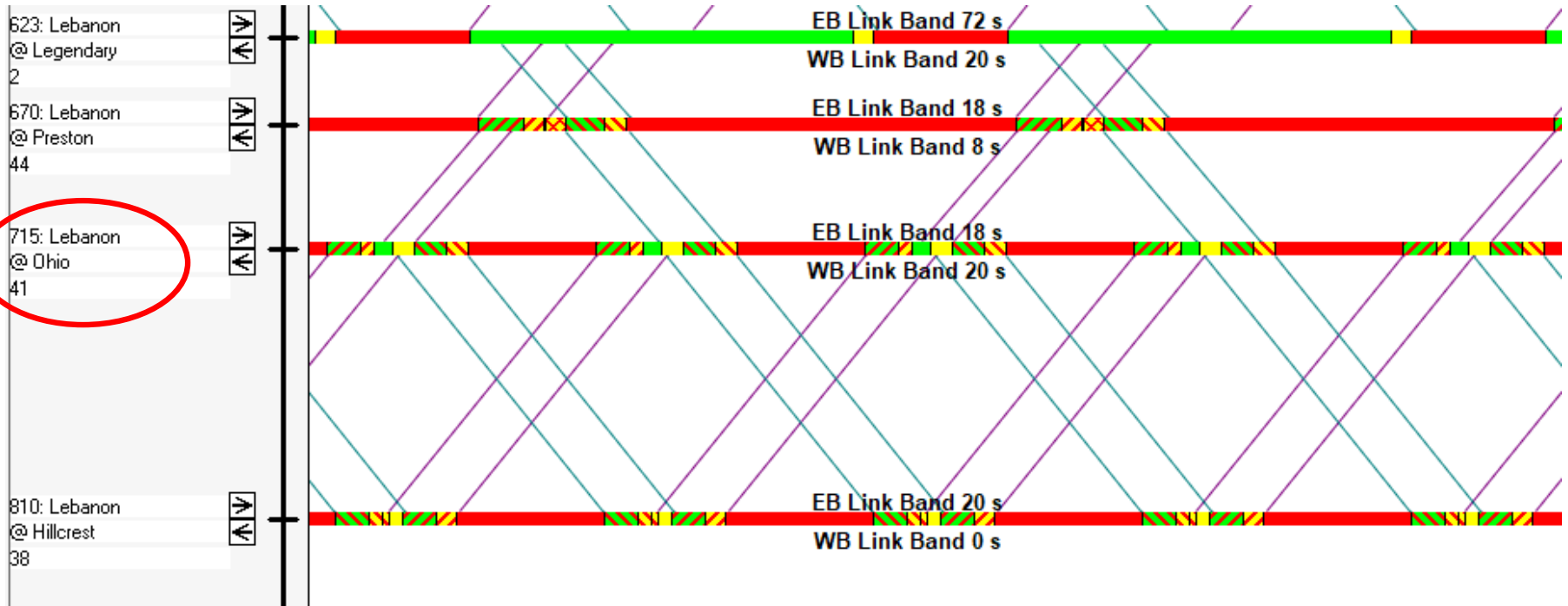
Ohio - Lebanon ATC 716 Signal 716 Phase: 8 Eastbound
Tuesday, May 8, 2018 12:00 AM - Tuesday, May 8, 2018 11:59 PM





PROGRESS IN MOTION

Case 2 – 30 to 80% GOR

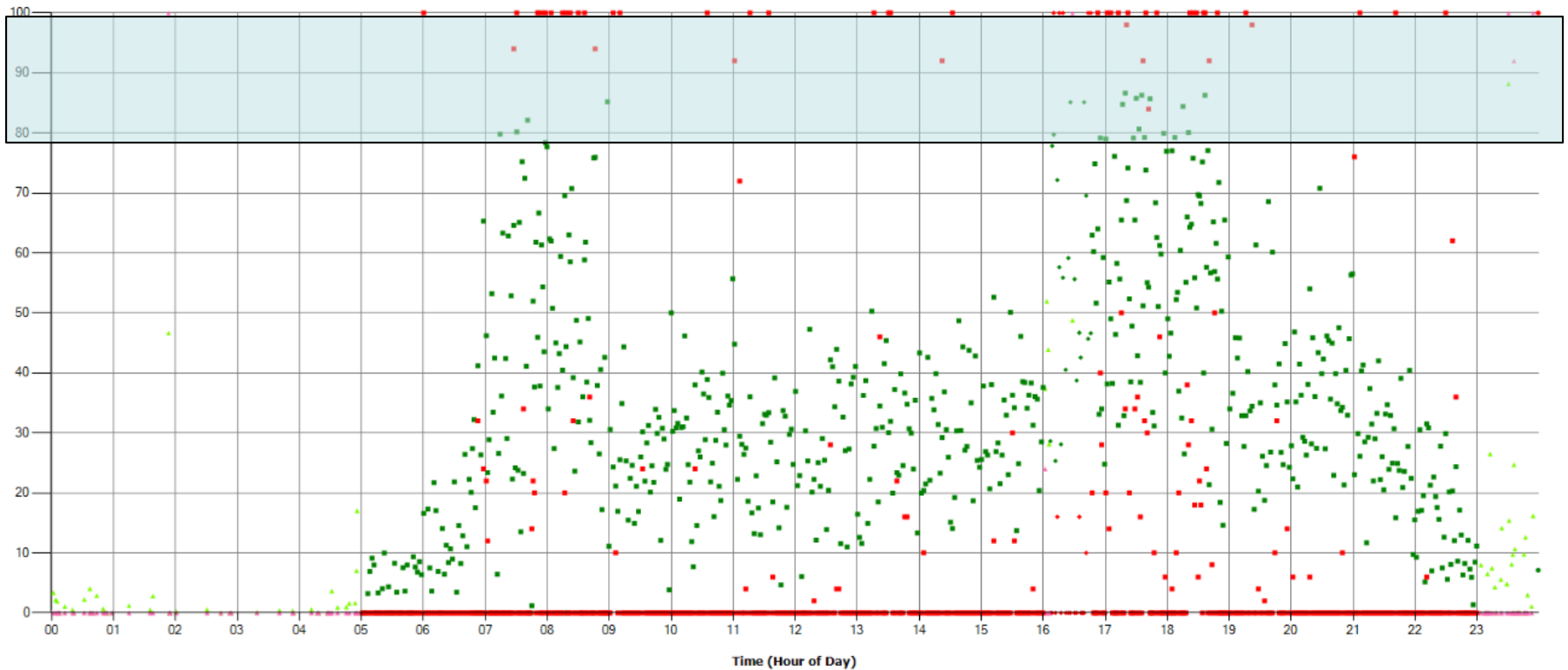




PROGRESS IN MOTION

Case 3 – 80 to 100% GOR

Ohio - Lebanon ATC 716 Signal 716 Phase: 8 Eastbound
Tuesday, May 8, 2018 12:00 AM - Tuesday, May 8, 2018 11:59 PM





PROGRESS IN MOTION

Case 3 – 80 to 100% GOR



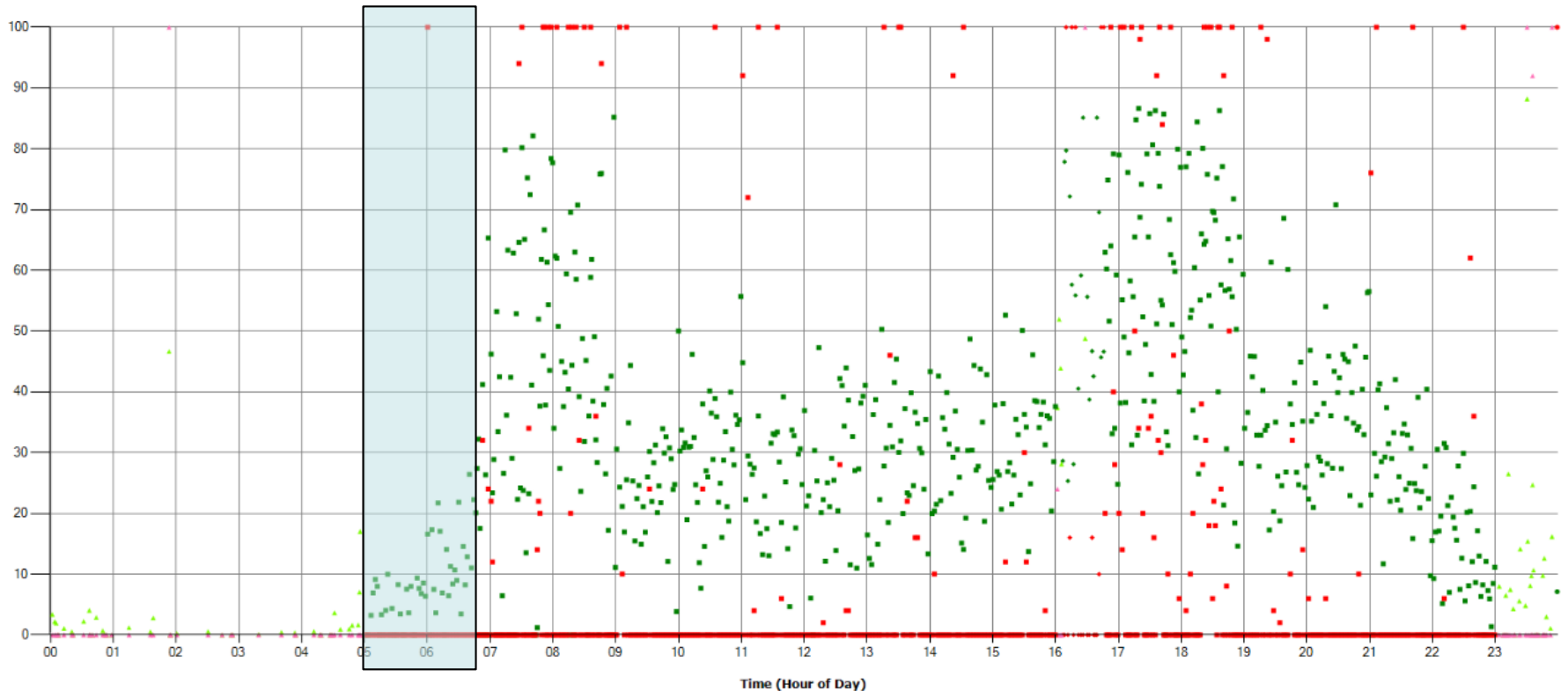


PROGRESS IN MOTION

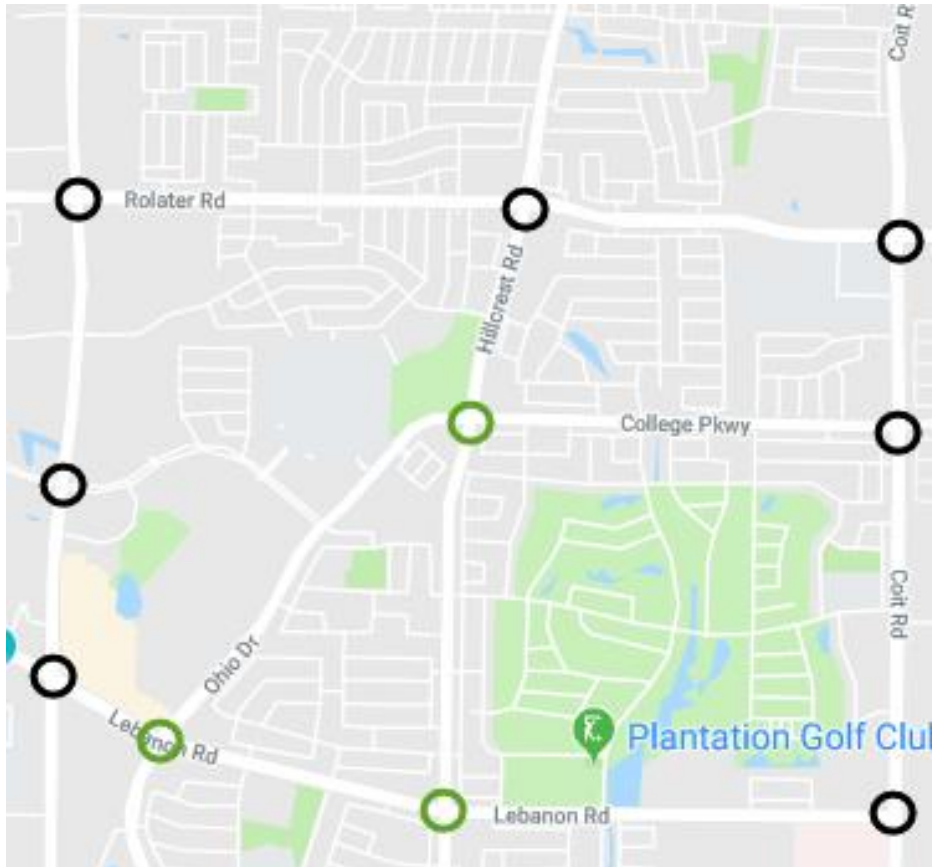
Use Case for GOR

- Changed from coordinated to free

Ohio - Lebanon ATC 716 Signal 716 Phase: 8 Eastbound
Tuesday, May 8, 2018 12:00 AM - Tuesday, May 8, 2018 11:59 PM



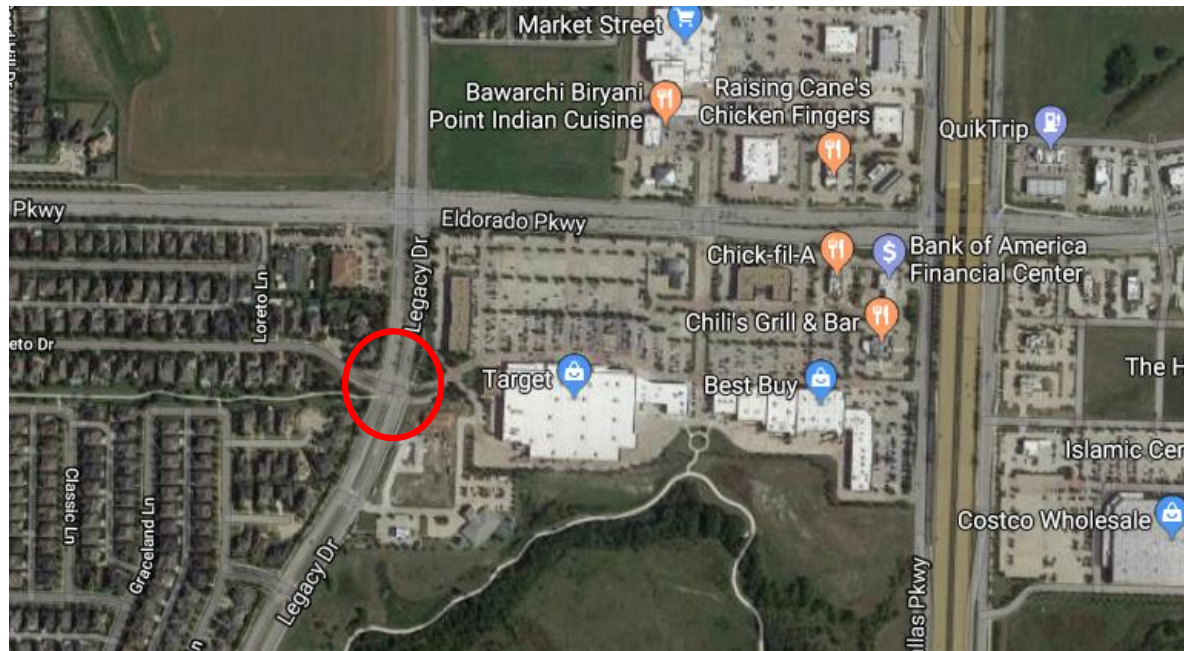
Use Case for GOR



- Green is Free
- Black is Coordinated

Phase Termination

- The chart versus the real world.
- Collected the data for Purdue Split Failure and recorded the approach.



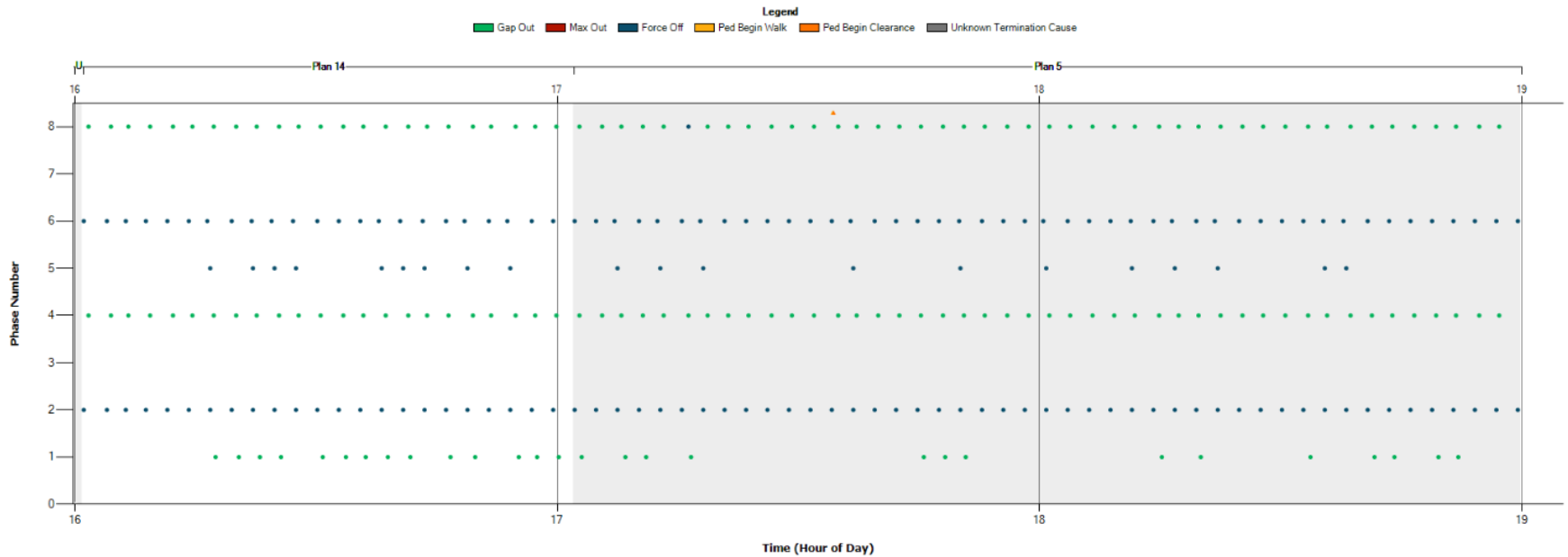


PROGRESS IN MOTION

Phase Termination

Legacy - Veneto ATC 266 Signal 266
Wednesday, May 9, 2018 4:00 PM - Wednesday, May 9, 2018 7:00 PM

Currently showing Force-Offs, Max-Outs and Gap-Outs with a consecutive occurrence of 1 or more.
Pedestrian events are never filtered



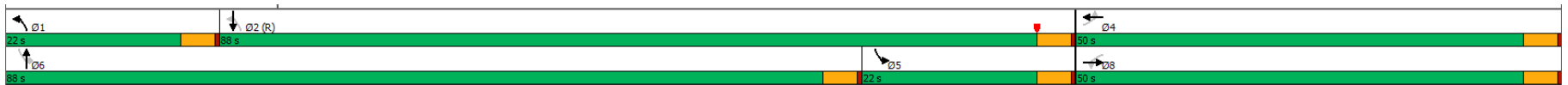
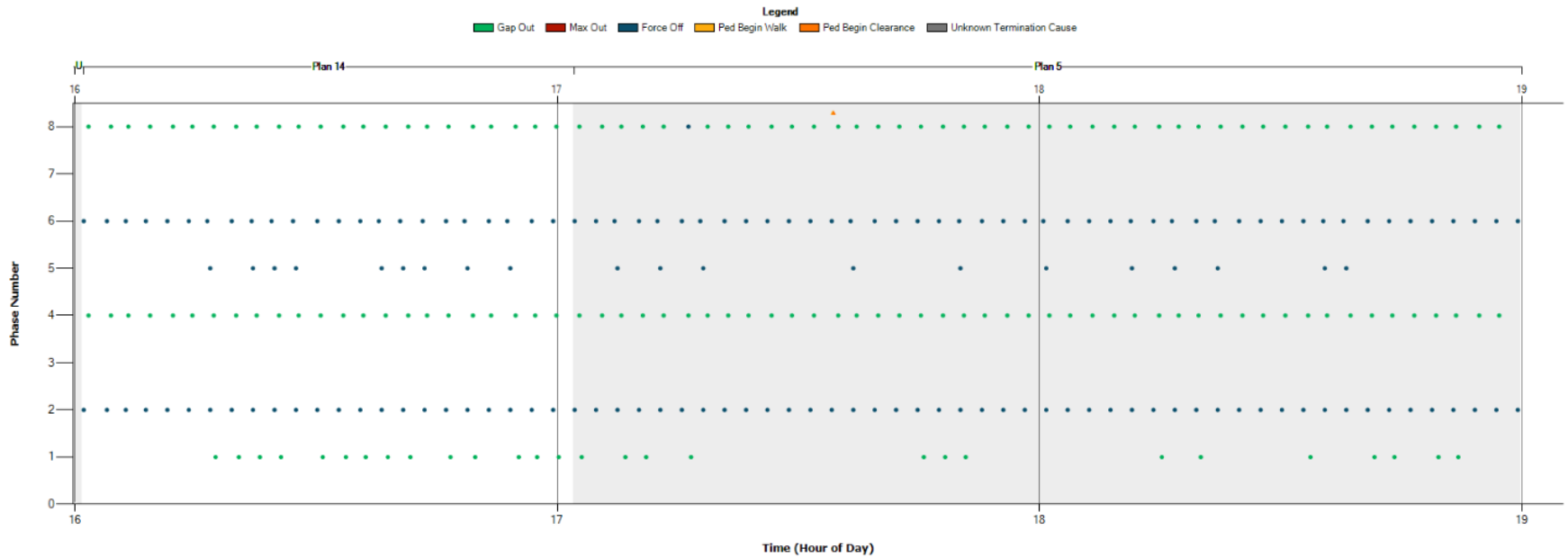


PROGRESS IN MOTION

Phase Termination

Legacy - Veneto ATC 266 Signal 266
Wednesday, May 9, 2018 4:00 PM - Wednesday, May 9, 2018 7:00 PM

Currently showing Force-Offs, Max-Outs and Gap-Outs with a consecutive occurrence of 1 or more.
Pedestrian events are never filtered





PROGRESS IN MOTION

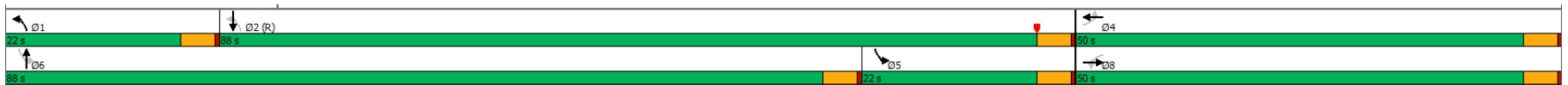
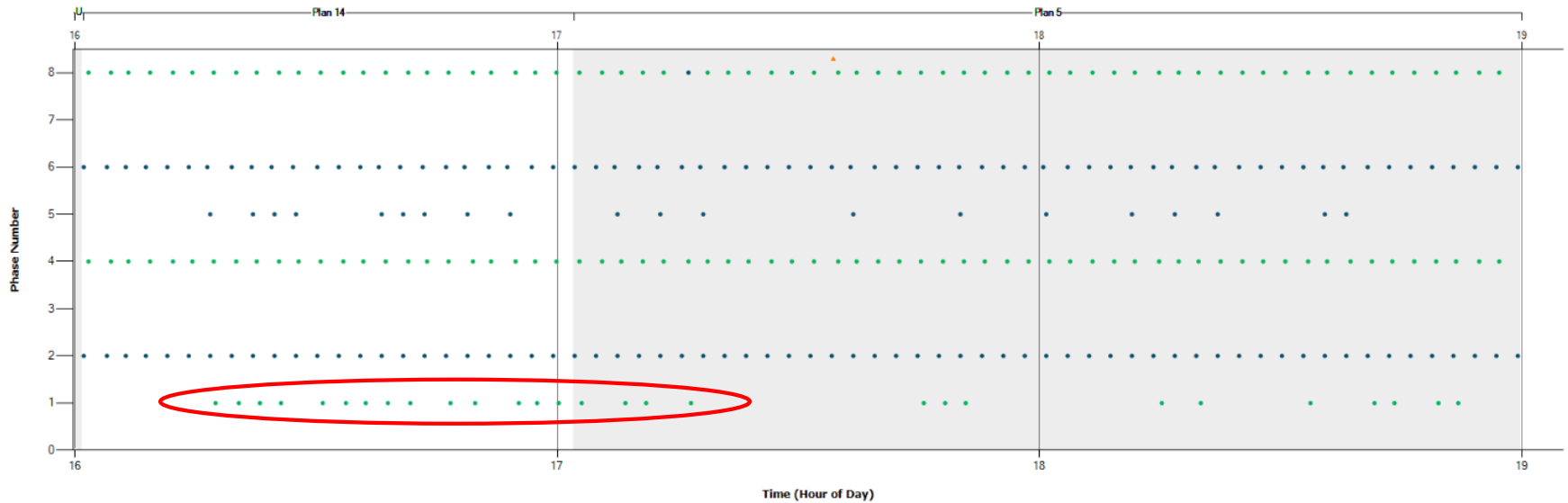
Phase Termination

Legacy - Veneto ATC 266 Signal 266
Wednesday, May 9, 2018 4:00 PM - Wednesday, May 9, 2018 7:00 PM

Currently showing Force-Offs, Max-Outs and Gap-Outs with a consecutive occurrence of 1 or more.
Pedestrian events are never filtered

Legend

Gap Out Max Out Force Off Ped Begin Walk Ped Begin Clearance Unknown Termination Cause





PROGRESS IN MOTION

Left Turn Cycle 1





PROGRESS IN MOTION

Left Turn Cycle 2



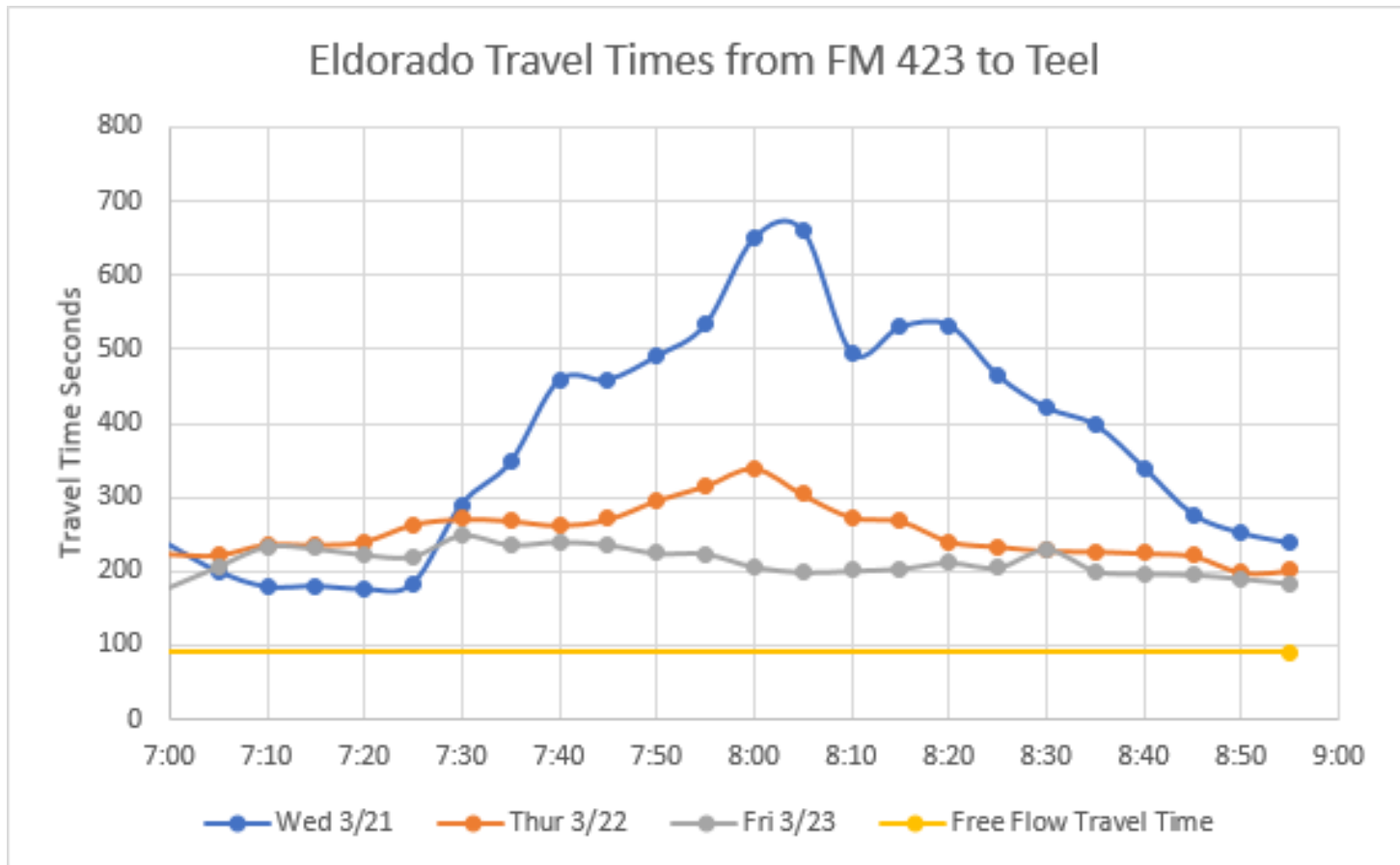


Crowd Source Travel Time

- Received an email – 10 minute backup, horrible.
- Watched traffic and made a signal timing change. Added 10 seconds of green.
 - Did I make the right change?
 - Did I change enough?

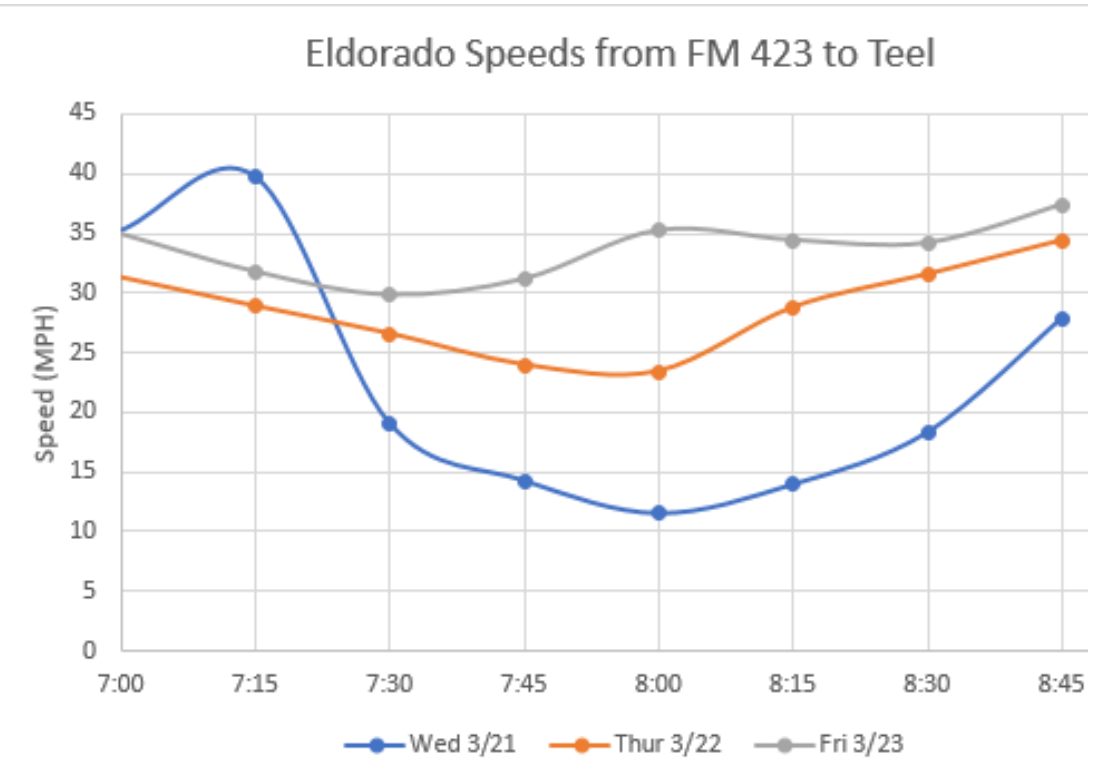
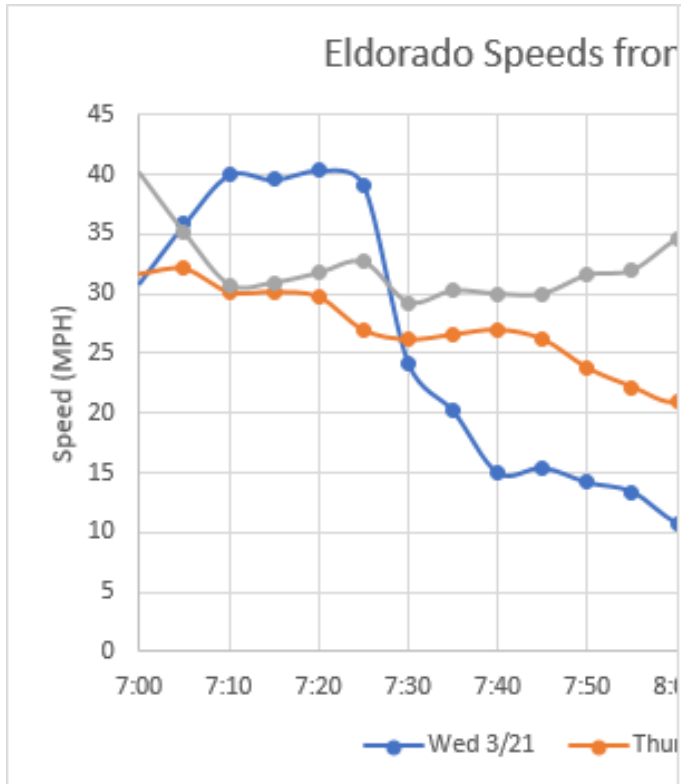
Crowd Source Travel Time

- Blue – Before, Orange – During, Gray - After



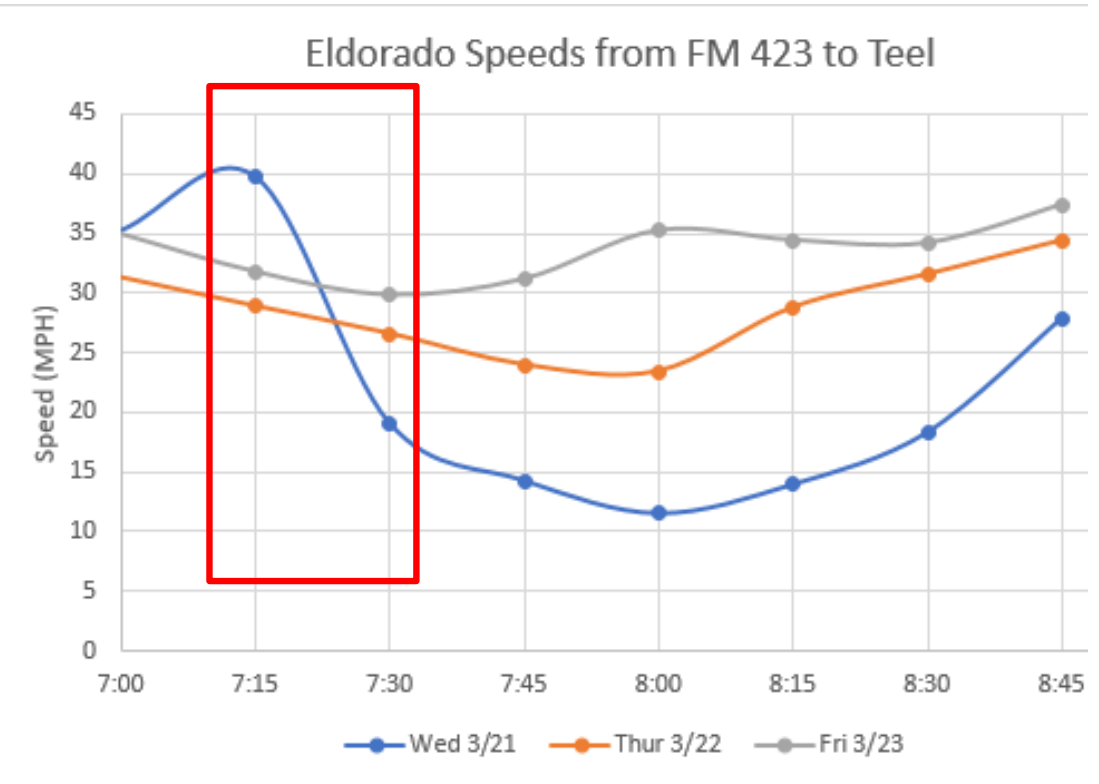
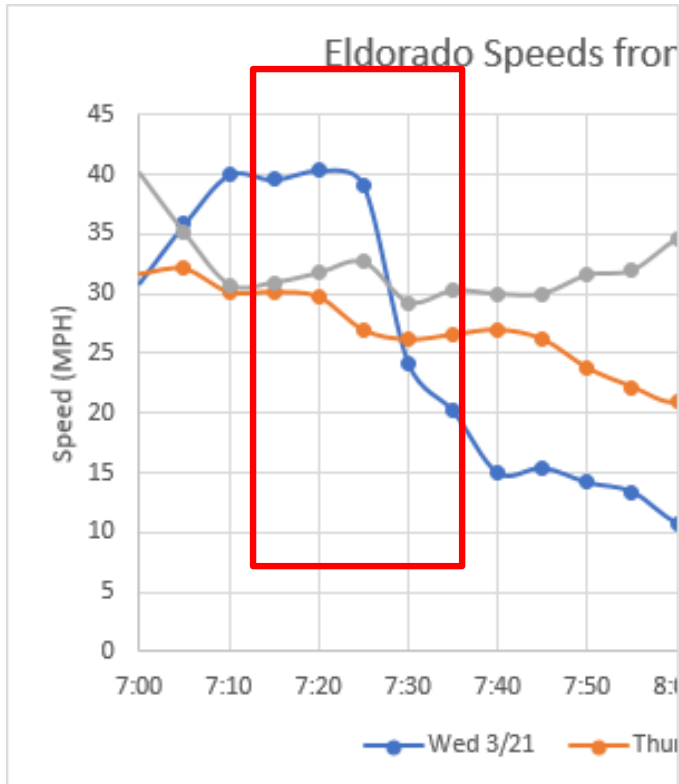
Crowd Source Travel Time

- 5 minute versus 15 minute data



Crowd Source Travel Time

- 5 minute versus 15 minute data.



Machine Learning

- Determine what in the SPM data indicates a problem. We need to gain experience.
- Machine Learning – user provides feed back to the SPM module.
 - Yes that was a traffic signal problem or
 - No that was not a traffic signal problem.
- From SPM (manual) to ATSPM (automated)
 - Data analytics that provide a “top 10 list” of problems, which are actually problems
 - Don’t need false alarms



Contact

Curtis Jarecki, P.E.
City of Frisco
cjarecki@friscotexas.gov
Tel: (972) 292-5457

